

### Lecture 1 – Introduction & Basic Switching

**Electric Drives Control** 

### We want torque !

- We are mainly interested in the mechanical torque on the electrical machine shaft
- But, the torque is the result of a complex interaction of electric voltages and currents, magnetic fluxes and mechanical layout
- Our source is (usually) a DC Voltage, that ...
  - we convert to AC with PWM and feed to the electrical machine to ...
  - control the machine currents such that the mechanical torque becomes the one we want.
- Against us we have:
  - A machine that require voltages that increase with speed
  - A battery with limited and almost constant voltage

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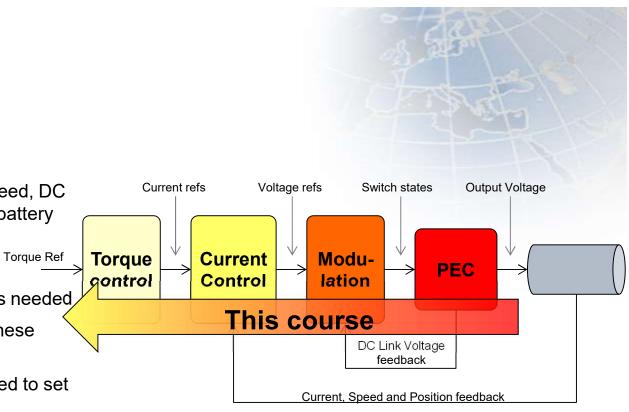
 A converter that needs to be controlled in a microsecond time scale

**Electric Drives Control** 



### How we do it?

- We start knowing:
  - The desired torque
  - Lots of system states, like speed, DC link voltage, phase currents, battery SOC, ...
- We calculate:
  - The traction machine currents needed
  - The voltages needed to set these currents
  - The modulation pattern needed to set these voltages
- We modulate the swithes accordingly !



**Electric Drives Control** 

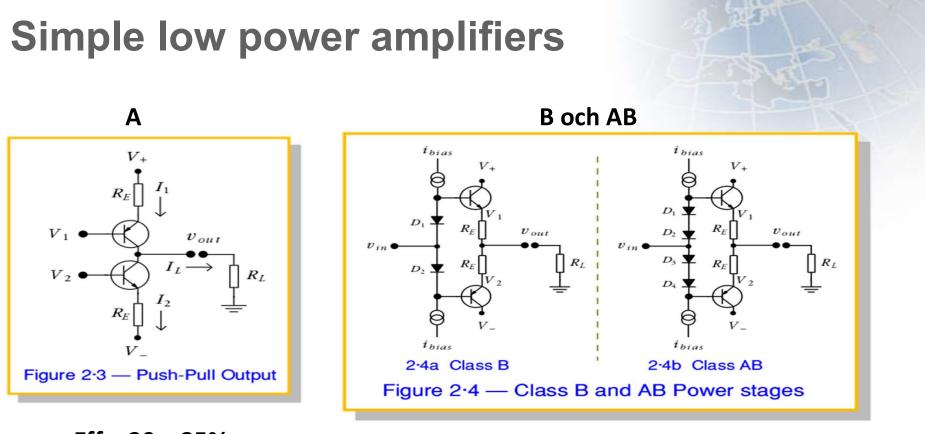
#### **Why Power Electronics?**

- The efficiency of a linear amplifier (converter) has a theoretical upper limit of 78.5 %
- This is sufficient in many low power applications, such as home audio
- In trains the rated power may be as high as 4-8 MW
- For an efficiency of 78.5 % the losses would be 0.86-1.72 MW
- This means that huge amounts of power and money would be lost

... but the main problem would be thermal management, i.e. handling the heat power

 Typically, the efficiency of a power electronic switch mode converter is >98 %





Eff = 20 – 25%

Eff = 60 %

**Electric Drives Control** 

#### **Class D Audio Amplifiers**



#### Hypex UcD2k 1x2000W Universal Class D Amplifier Module

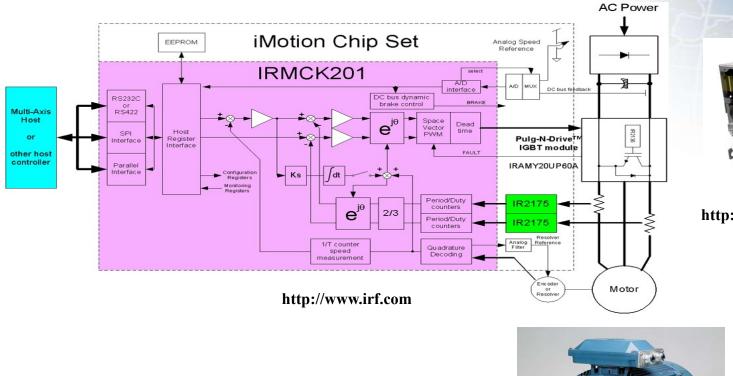
The UcD2k amplifier module is an entry level high-end class D amplifier from Hypex. The UcD2k is known for its high performance, reliability and ease of use. The UcD2k comes with the required UcD Signal Cable.

Specifications for: UcD2k	1x2000W Universal Class D Amplifier Module
Rated power output (RMS) 0	2500 watts at 4 ohms 1600 watts at 8 ohms 2000 watts at 2 ohms
Minimum load	1 ohm
Efficiency	92 %
Signal-to-noise ratio (SNR)   🕕	
Distortion 🚯	0.02 % (20-20.000 Hz @ 0.5 x Rated power output)
Frequency response	10 - 50,000 Hz
Gain	34 dB
Input sensitivity	2.25 Vrms for rated power output
Input impedance	100k ohms
Amplifier Classification	Class D
Circuit Topology	UcD®
Speaker output channels	1
Power Requirements	50 - 98 VDC (symmetric supply +/-) 13 - 15 VDC (driver supply voltage)
Power inlet connector	Crimp/solder connection tabs
Current limit	50 A
Under/over voltage protection	~
Dimensions (L x W x H)	141 x 108 x 38 mm

#### What is Power Electronics used for?

- All kinds of electrical drives where electrical power is transferred to mechanical and variable speed is required such as
  - Traction applications such as trains, electrical vehicles and ship propulsion
  - Pumps and fans
- All kinds of electrical drives where electrical power is transferred to mechanical and position control (servo) is required such as
  - Robots, cranes
- Power system applications such as
  - HVDC (up to 3000 MW), Transistor based HVDC
  - Feeding and priming power from renewable energy sources (solar, wind, ...)
  - Active power filters, reactive power compensation, ...
- Power supplies
  - Computers, tv-sets, ...
  - Battery chargers for computers, mobile phones, hand-held tools, ...
- Back-up power, i.e. uninteruptable power supplies
- Many other applications

#### **Electrical Motor Drives**





http://www.semikron.com

http://www.abb.com



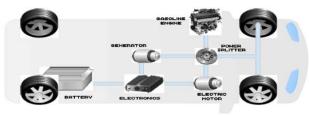
#### **Typical Motor Drive Applications**

- Except pumps, fans, cranes, ...

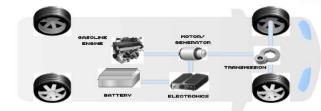
#### **Traction: for example trains and hybrid vehicles**



Series Hybrid http://www.hybridcenter.org/



Series-Parallel Hybrid http://www.hybridcenter.org/



Prallel Hybrid http://www.hybridcenter.org/

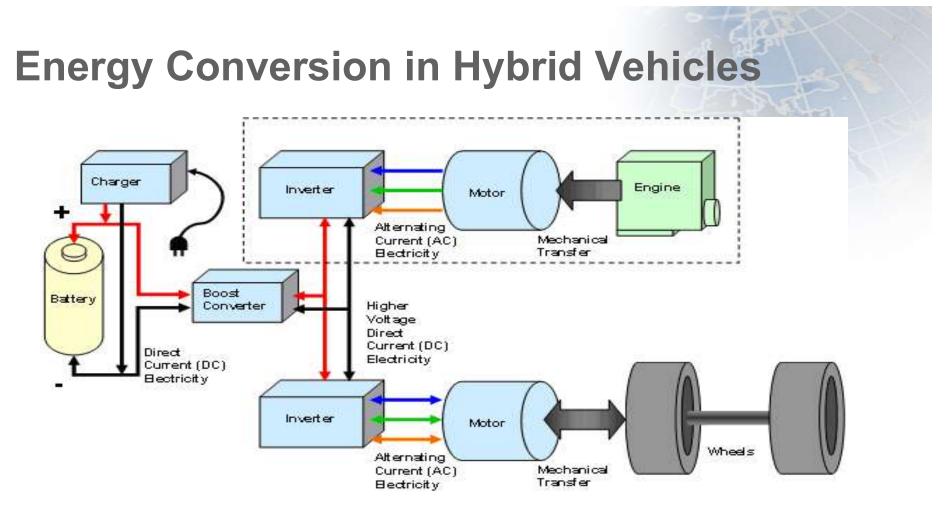


http://www.toyota.com/

#### Robotics



http://www.abb.com



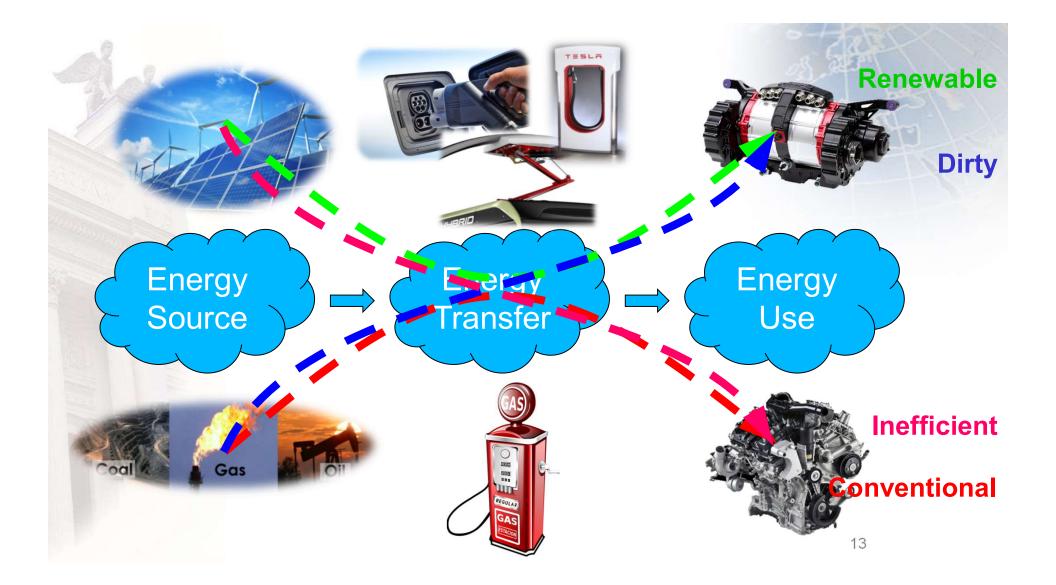
**Electric Drives Control** 



## **EV Charging**



Professor Mats Alaküla Industrial Electrical Engineering at Lund University Senior Technology Advisor, AB Volvo Scientific Leader, Swedish Electro Mobility Research Centre





### The last Century

### The Charging Challenge is NOT new ...

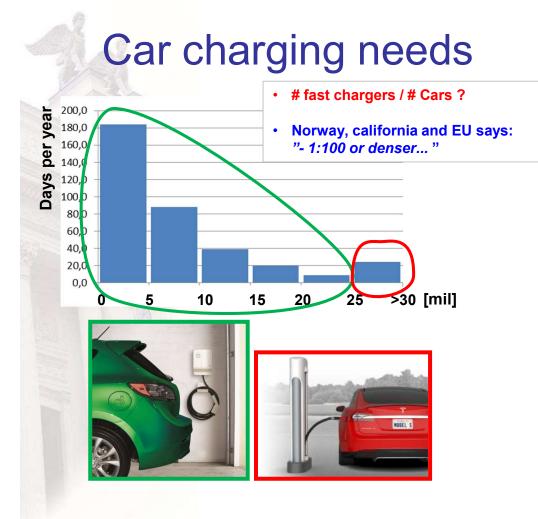








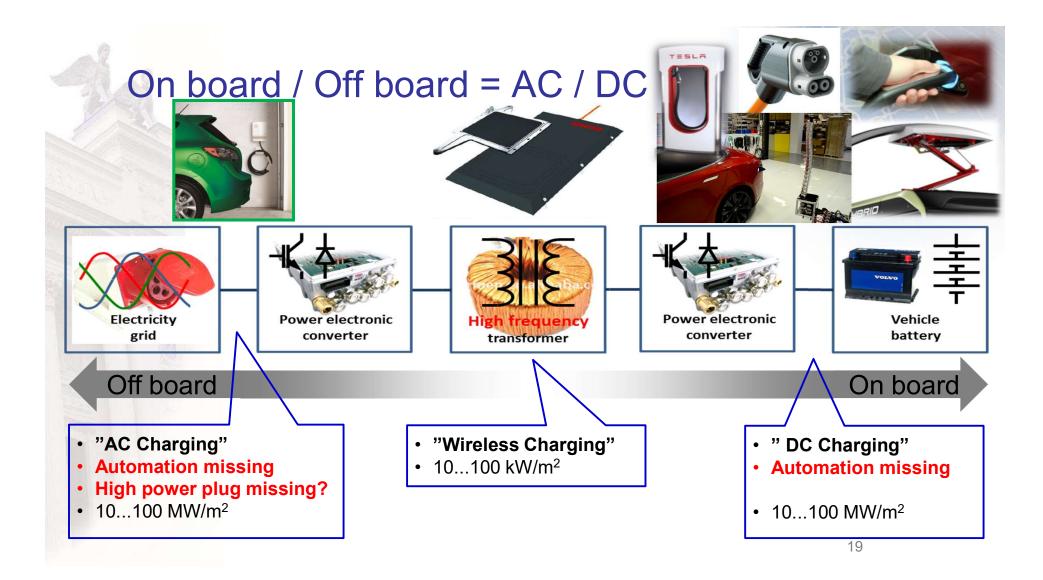
### Possibilities

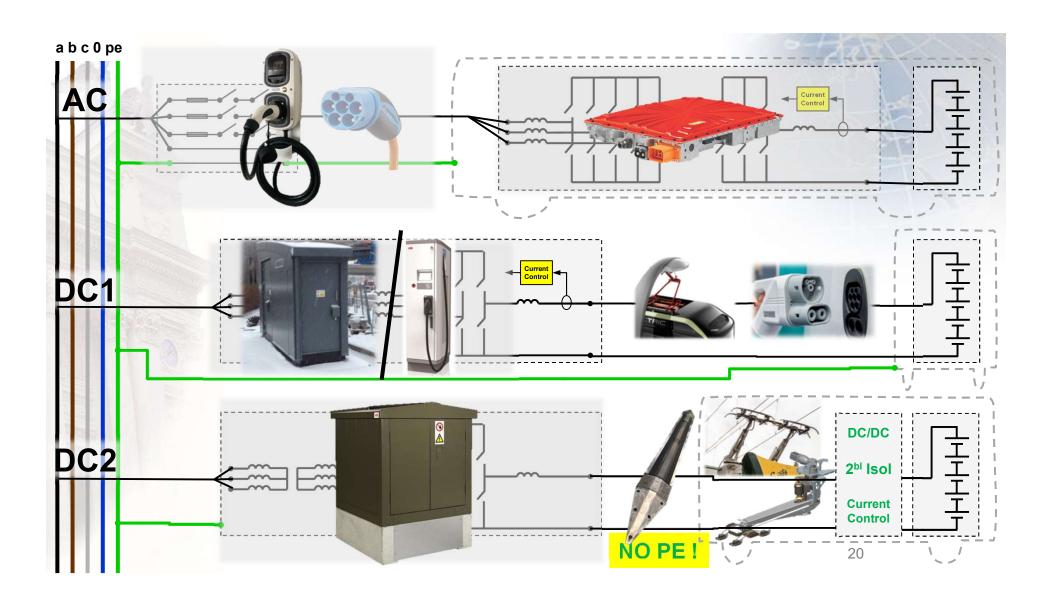


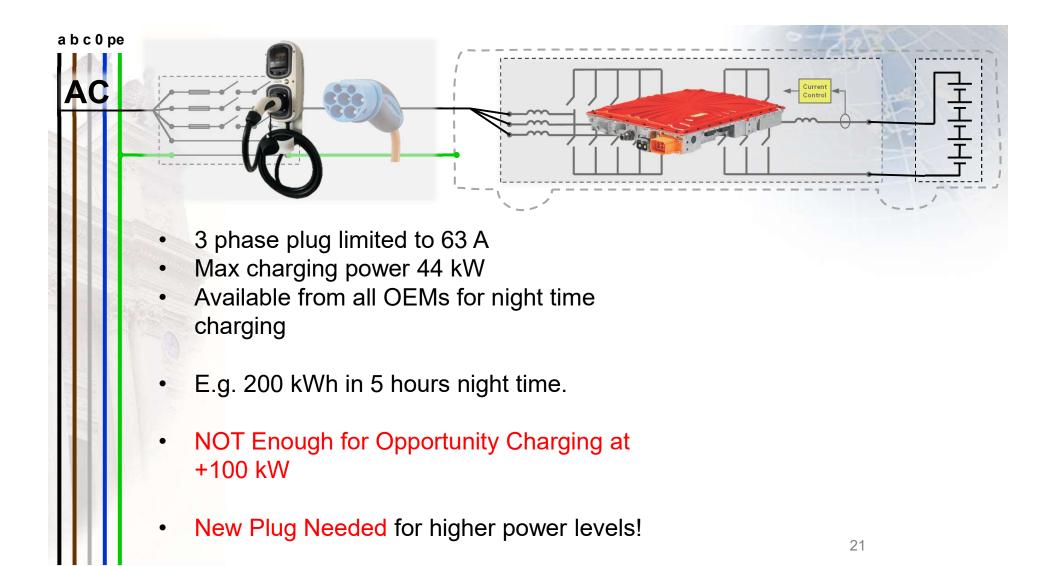


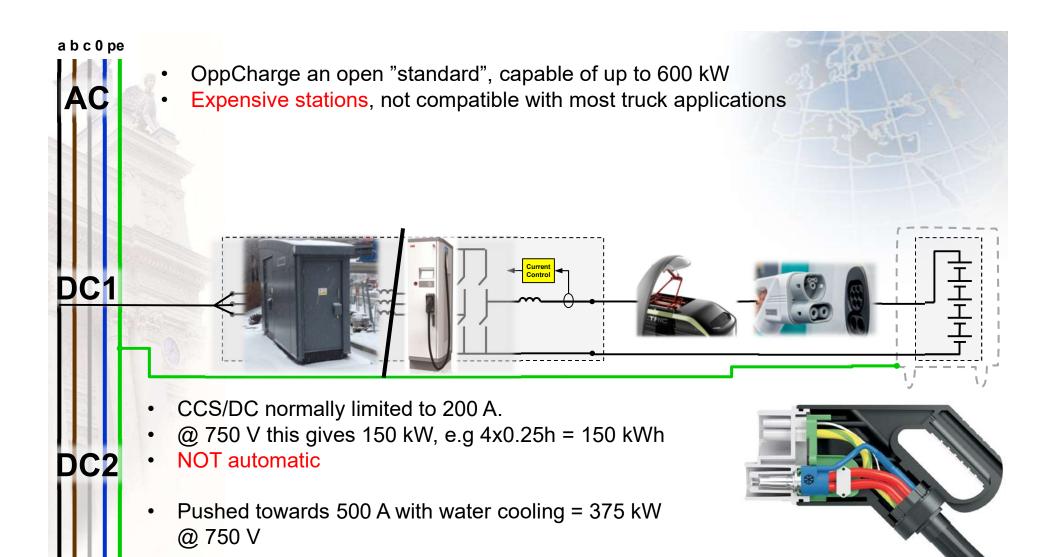


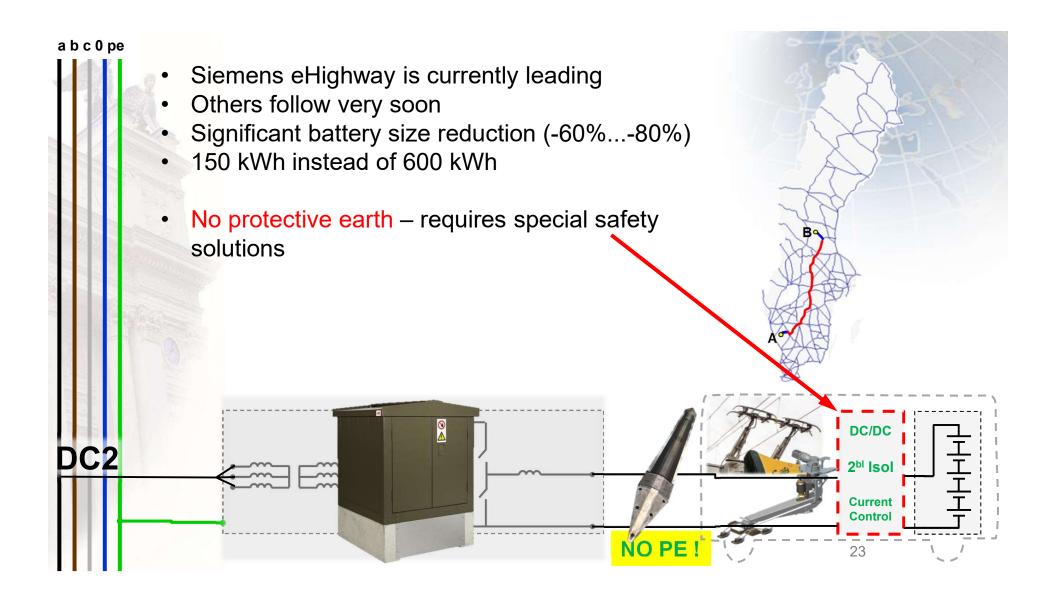
## **Static Charging**











### Tesla Semi Analysis ...





#### **Technical facts**

#### **Given Facts**

- GVW = 80000 lbs = 36 287 kg
- Drag Coefficient = Cd = 0.36
- Drivetrain: 4 PM motors from Model 3
- Acceleration 0-60 mph = 0-97 km/h
- Tractor only: 5 seconds
- Full load (80000 lbs): 20 seconds
- Hill climbing: 5 % slope @ 65 mph = 105 km/h
- Range: 300/500 miles = 483/805 km
- Charging time: 400 miles = 644 km in 30 minutes

#### **Calculated Facts**

- Energy consumption = about 1 kWh/km
- Tractor weight = 9 tons
- Traction motors = 4 x 137/192 kW (cont/peak)
- Battery Energy = 850 950 kWh (depends on DoD)
- Battery Weight = 4.2 4.7 tons (@ 0.2 kWh/kg)
- Charging power
  - = almost 1.3 Megawatt for Fast Charging
  - = 100 kW for Night Time Charging
- MEGA Charging Connector: Seems to be 4xSUPER Charging Connector







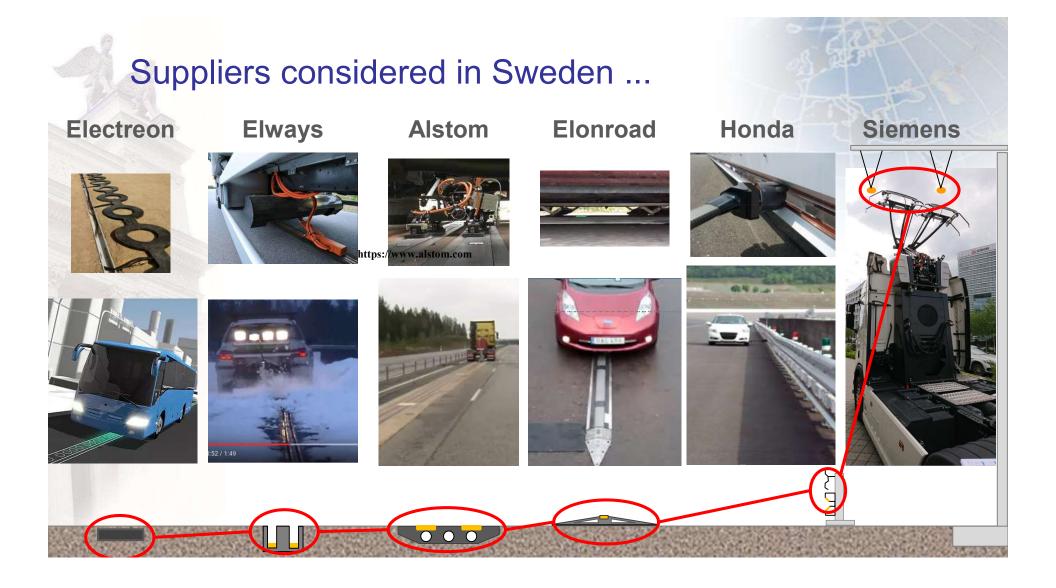
Volvo Trucks. Driving Progress

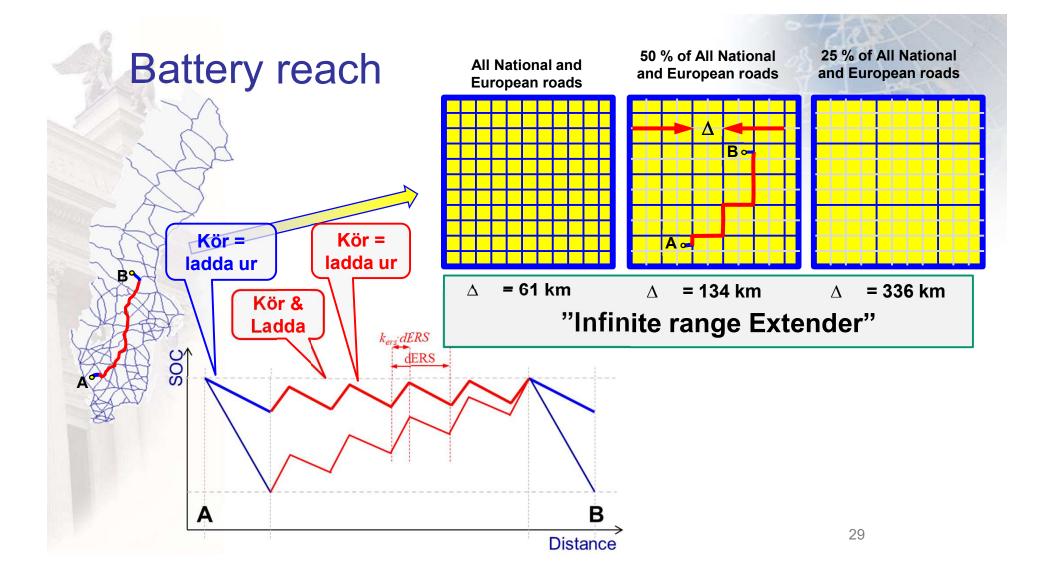
## **Dynamic Charging**

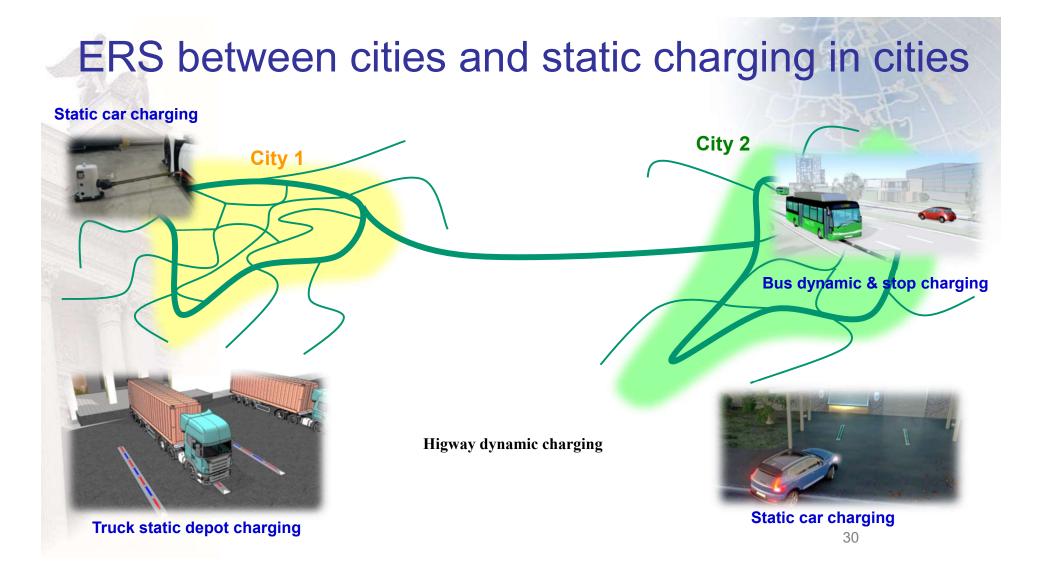
#### Electric Road Systems (ERS) – Continuous charging

- Transfer energy to vehcles in motion
- Traditionally in Trains, Trams and Trolley Buses
- Different technologies, different connections
- Several different technology demonstrations under way

	Тор	Side	Below
Conductive			
Inductive	Х	X	
Capacitive	X	X	Point Comment

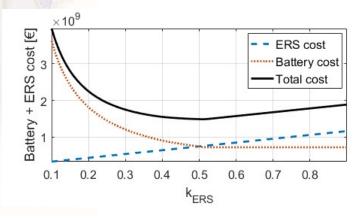


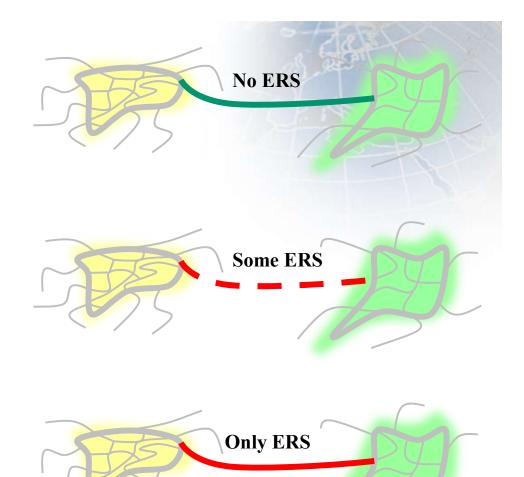




### Not ERS all the way...

- No ERS
- = No ERS cost, high battery cost
- Some ERS
  - = Reduced battery cost, some ERS cost
- Only ERS
  - = Low battery cost, high ERS cost
- There is an optimum





### **Possibilities and Challenges**

- Possibilities:
  - Large reduction of battery need (-50% ... -80%)
    - Cheaper, lighter and more energy efficient vehicles
  - No need for fast chargers
    - Only night time + ERS
- **Challenges** 
  - Road installation and maintenance
  - Electro magnetic, thermal and mechanical safety
  - Legal and business aspects

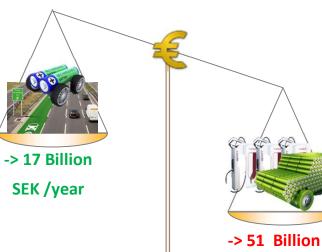


#### A fast cost comparison

- 5 million cars á 15 kWh
  batteries á 1000 SEK/kWh @
  10 years lifetime
  -> 7 Billion SEK/year
- 50 000 Heavy Duty Trucks á 100 kWh batteries á 1000 SEK/kWh @ 2 years lifetime

-> 2 Billion SEK/year

 15 600 km National and European road á 10 Million SEK/km @ 20 years lifetime -> 8 Billion SEK/year



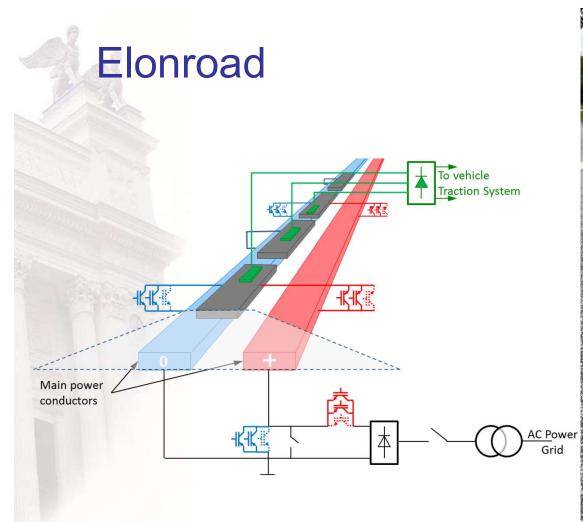
SEK /year

- 5 million cars á 75 kWh batteries á 1000 SEK/kWh
   @ 10 years lifetime
   -> 38 Billion SEK/year
- 50 000 Heavy Duty Trucks á 500 kWh batteries á 1000 SEK/kWh @ 2 years lifetime

-> 12 Billion SEK/year

 50 000 "SuperChargers" á 150 kW á 6000 SEK/kW @ 25 years lifetime
 -> 1 Billion SEK/year

500 "**MEGA**Chargers" á 1000 kW á 6000 SEK/kW @ 25 years lifetime -> 0,12 Billion SEK/year





# Other applications of Power Electronics

### **Frequency Conversion**

- Japan East / West
- 50/60 Hz
- 600 MW





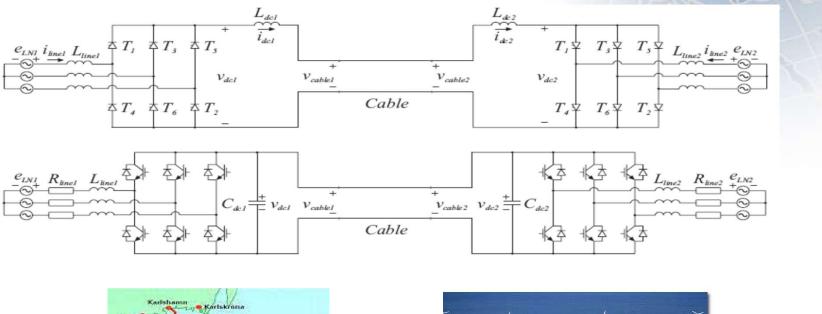
# HVDC

• Japan: Hokkaido to Honshu / 600 MW





### **HVDC and Transistor Based HVDC**



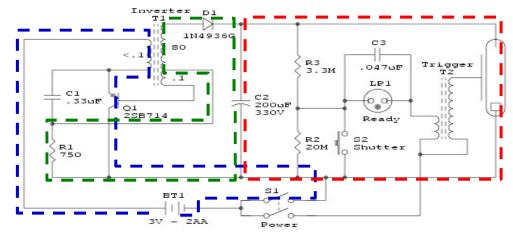


http://swepollink.svk.se/



http://www.abb.com/

## **Camera with flash**



Kodak Ektralite 10 Flash Unit



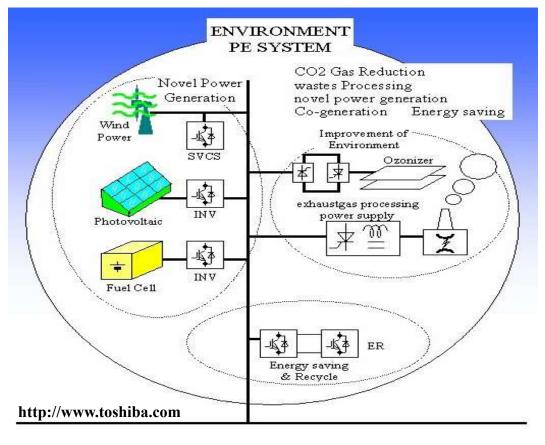
# **Audio amplifiers**



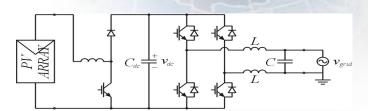


Electric Drives Control

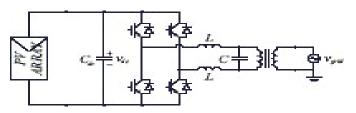
#### **Renewable Energy Systems**



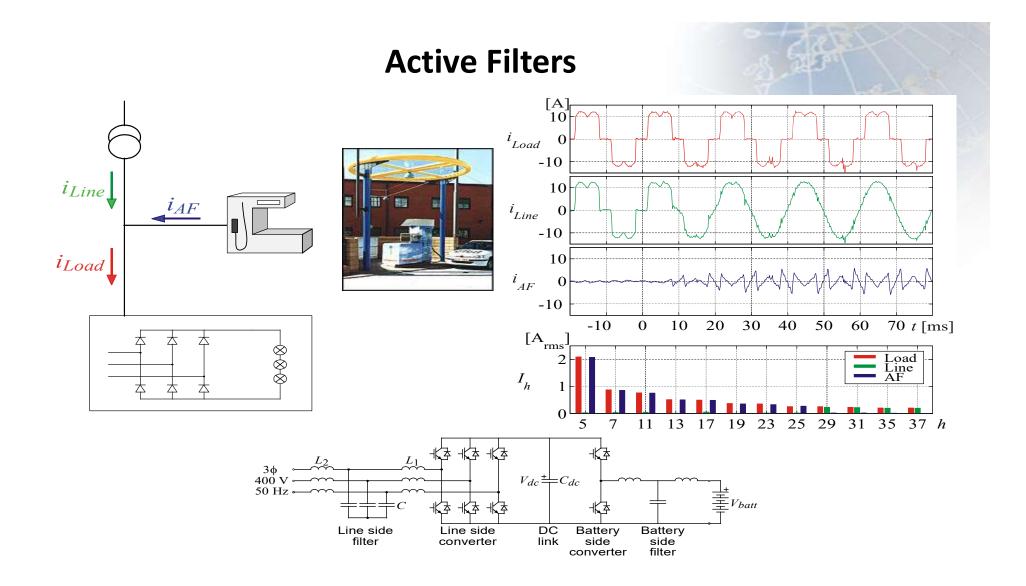
**Converters Suitable for Solar Cells** 



#### Without transformer

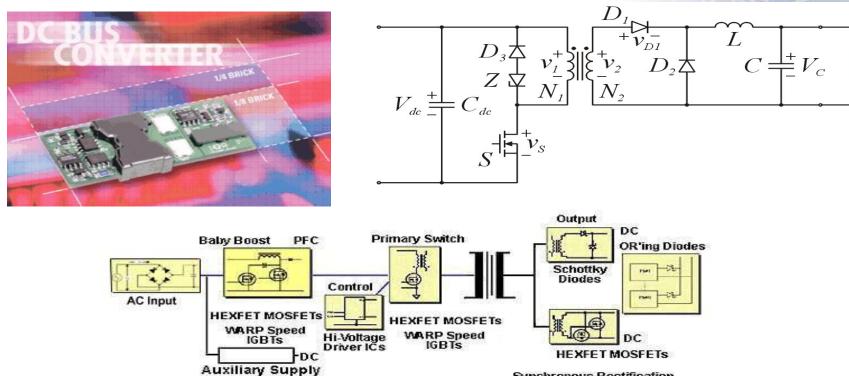


With transformer



### **Switch Mode Power Supplies**

#### - Forward Converter



Synchronous Rectification

 $R_{\scriptscriptstyle load}$ 

http://www.irf.com

# **Thank You!**





# The Course 2021

- Lectures 2 times a week
- 2...3 exercises a week
- 6 labs with home assignments / simulation exercises:
  - The Flyback Converter
  - The H-bridge
  - Speed Control with a DC Machine
  - Control of an Active Power Filter
  - Control of PM Machines
  - Control of Induction Machines



# **Teaching Plan 2021**

Calendar Week	Date	Time	Event Lecture, Exercise, Preparation	Торіс	Teacher	Note (deadlines)
3	2021-01-18	15:15-17:00	L	Intro + Semiconductors and bridges	Mats	
	2021-01-19	13:15-15:00	L	Bridges, switch dynamics, snubbers	Mats	
	2021-01-21	13:15-15:00	E	Semiconductors, bridges etc	Mats	
	2021-01-21	15:15-17:00	E	Semiconductors, bridges etc	Mats	
	2021-01-22	10:15-12:00	p	Flyback Simulation preparation (Ltspice)	Akanksha	
4	2021-01-25	13:15-15:00	L	DC/DC conv +1 phase modulation	Mats	
	2021-01-25	15:15-17:00	E	DC/DC conv +1 phase modulation	Mats	
	2021-01-27	10:15-12:00	P	Flyback Lab preparation	Akanksha	Flyback simulation report
	2021-01-27	13:15-15:00	L	H-bridge + 2 phase modulation (+ thermal)	Mats	
	2021-01-29	10:15- <mark>12:0</mark> 0	P	H-bridge Simulation preparation (+ support an Flyback Lab)	Akanksha	
5	2021-02-01	13:15-15:00	L	Position and Speed control	Mats	
	2021-02-01	15:15-17:01	E	Position and Speed control	Mats	
	2021-02-03	10:15-12:00	L	DC Current Control	Mats	Flyback lab report
	2021-02-03	13:15-15:00	E	DC Current Control	Mats	
	2021-02-05	08:15-10:00	P	H-bridge Lab preparation + thermal	Akanksha	H-bridge simulation report
	2021-02-08	13:15-15:00	L	Torque generation	Mats	
6	2021-02-08	15:15-17:01	E	Torque generation	Mats	
	2021-02-10	10:15-12:00	L	DC Machine Theory and Control	Mats	
	2021-02-10	13:15-15:00	E	DC Machine Theory and Control	Mats	
	2021-02-12	08:15-10:00	P	DC-machine Simulation preparation	Samuel	H-bridge lab report
7	2021-02-15	13:15-15:00	L	AC-power + 3 phase modulation	Mats	
	2021-02-15	15:15-17:01	E	AC-power + 3 phase modulation	Mats	
	2021-02-17	10:15-12:00	P	DC-machine Lab preparation	Samuel	DC-machine simulation report
	2021-02-17	13:15-15:00	L	AC Current Control	Mats	
	2021-02-19	08:15-10:00	E	AC Current Control	Mats	2)) 
8	2021-02-22	13:15-15:00	L	Static VAr compensation	Mats	1
	2021-02-22	15:15-17:01	E	Static VAr compensation	Mats	
	2021-02-24	10:15-12:00	L	Active Filters, design & control	Mats	
	2021-02-24	13:15-15:00	E	Active Filters, design & control	Mats	· · · · · · · · · · · · · · · · · · ·
	2021-02-26	08:15-10:00	L	Guest lecture Active Power Filters	Mats	DC-machine lab report
9	2021-03-01	13:15-15:00	L	Passive components (Ind⋒)	Mats	
	2021-03-01	15:15-17:01	E	Passive components (ind⋒)	Mats	
	2021-03-03	10:15-12:00	L	Inductor design	Mats	
	2021-03-03	13:15-15:00	E	Inductor design	Mats	
	2021-03-05	08:15-10:00		Spare	Mats	
10	No teaching					
11	Exam period					

Calendar Week	Date	Time	Event Lecture, Exercise, Preparation	Торіс	Teacher	Note		
12	2021-03-23	13:15-15:00	L	Synchronous Machine and PMSM	Mats			
	2021-03-23	15:15-17:01	E	Synchronous Machine and PMSM	Mats			
	2021-03-25	13:15-15:00	Ρ	AF simulation preparation	Max			
	2021-03-25	15:15-17:01	L	Control of PMSM, incl FW	Mats			
13	2021-03-30	13:15-15:00	E	Control of PMSM, incl FW	Mats			
	2021-03-30	15:15-17:01	L	Semiconductor I	Mats			
	2021-03-31	13:15-15:00	E	Semiconductor I	Mats	·		
	2021-03-31	15:15-17:01	Ρ	AF lab preparation	Max	AF simulation report		
14	Exam period							
15	Exam period							
16	2021-04-20	13:15-15:00	L	Semiconductor II	Mats	8		
	2021-04-20	15:15-17:01	Ε	Semiconductor II	Mats			
	2021-04-22	13:15-15:00	L	Thermal modelling (losses)	Mats			
	2021-04-22	15:15-17:01	Р	PMSM simulation preparation	Samuel	AF lab report		
17	2021-04-27	13:15-15:00	Ε	Thermal modelling (Losses)	Mats			
	2021-04-27	15:15-17:01	P	PMSM lab preparation	Samuel			
18	2021-04-04	13:15-15:00	L	Thermal modelling (Cooling)	Mats			
	2021-04-04	15:15-17:01	Ε	Thermal modelling (Cooling)	Mats	PMSM simulation report		
	2021-04-05	13:15-15:00	L	IM Modelling and Control	Mats			
	2021-04-06	15:15-17:01	Ε	IM Modelling and Control	Mats			
19	2021-05-11	13:15-15:00	Ρ	IM simulation preparation	Samuel			
	2021-05-11	15:15-17:01	L	EMCI	Mats	PMSM lab report		
20	2021-05-18	13:15-15:00	E	EMCI	Mats			
	2021-05-18	15:15-17:01	Ρ	IM lab preparation	Samuel	1		
	2021-05-20	13:15-15:00	L	Guest lecture	TBD	IM simulation report		
	2021-05-20	15:15-17:01	( <b>*</b> )	Spare	-			
21	2021-05-25	13:15-15:01	L	Resonant and Multilevel converters	Mats			
	2021-05-25	15:15-17:02	Ε	Summary and recap before exam	Mats			
	2021-05-27	13:15-15:01	Р	Exam preparations	Mats	IM lab report		
	2021-05-27	15:15-17:02	Р	Exam preparations	Mats			
22	2020-06-03	15:00-19:00		Written Exam				

# **Home Assignments**

- Content as similar as possible to the labs
- Prepares you for the lab
- Diagnostic tests can be used before the labs You must pass!



# **Covid-19 limitations**

- To start with, we will do everything via Internet
  - Lectures, Exercises, Labs
- IF, or WHEN, it is possible, we will return to F2F teaching
- The Labs are the trickiest part !
  - Based on filmed lab moments that you analyse



Electric Drives Control

## **Teachers**

- Lectures:
  - Mats Alaküla, professor
- Course assistance, simulation exercises and Labs:
  - Akanksha Upadthey, PhD student
  - Max Collins, PhD student
  - Samuel Estenlund, PhD Student

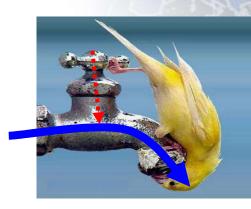


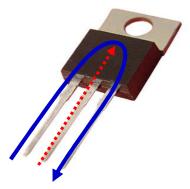


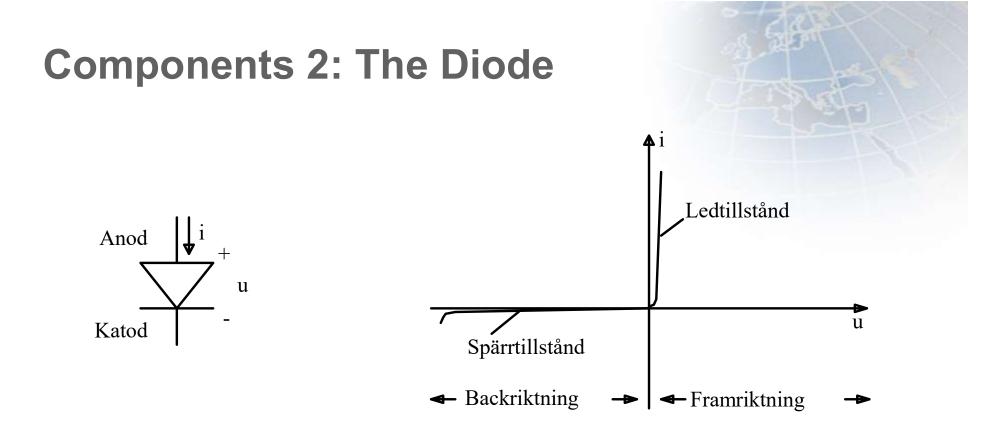
# Components

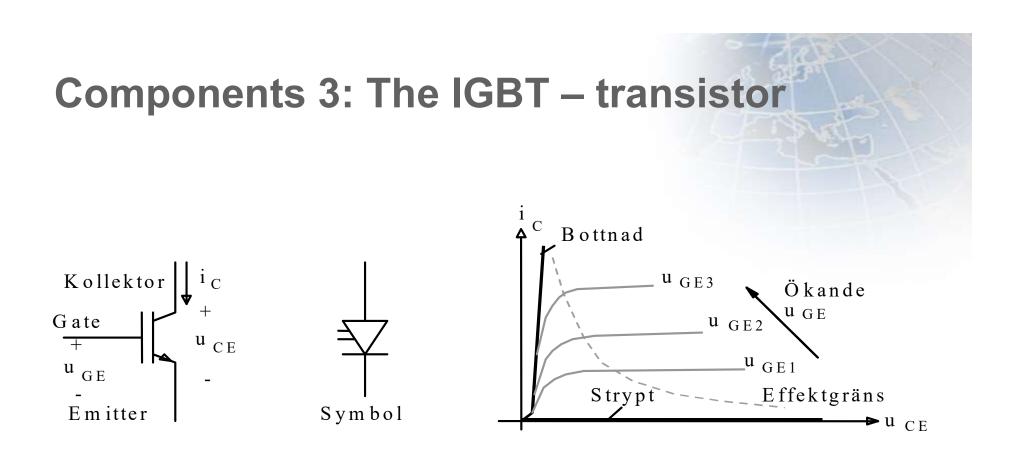
# **Components 1 : The transistor**

- · Works like a valve for electric current
- Compare to a water tap
  - Control a big flow with a small movement
  - Flow x Pressure drop = Power
  - Heats the water (a little)
- A transistor
  - Controls a big current with a small current
  - The voltage drop across the transistor x the current = Power
  - Heats the transistor (a lot)





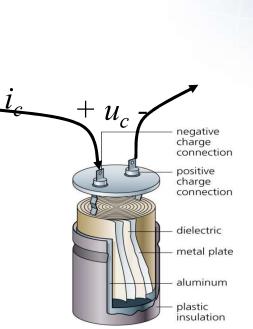




# **Components 4: The Capacitor**

 Stores electric current with increasing voltage like a hydrophore stores a fluid or gas with increasing pressure

$$\frac{du_c}{dt} = \frac{1}{C} \cdot i$$



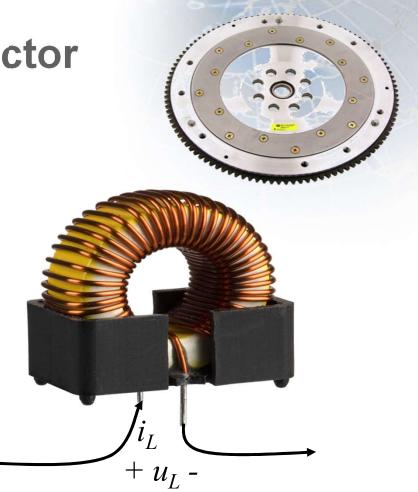




# **Components 5: The Inductor**

 Stores currrent into magnetic energy like a flywheel stores torque into speed and mechanical energy

$$\frac{di_{L}}{dt} = \frac{1}{L} \cdot u_{L}$$

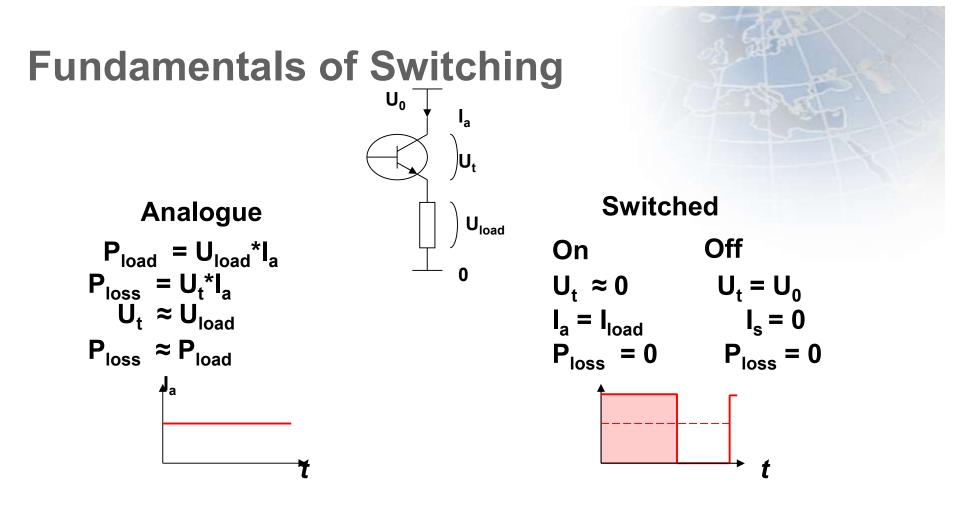


Never break an inductive current Never short a capacitive voltage





# **Basic Switching**



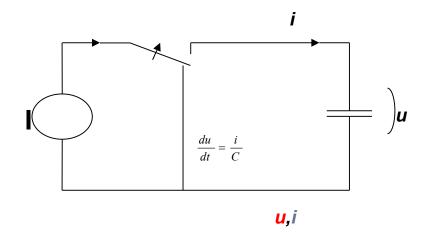
**Electric Drives Control** 

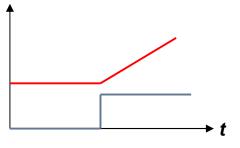
## Never break an inductive current Never short a capacitive voltage



**Electric Drives Control** 

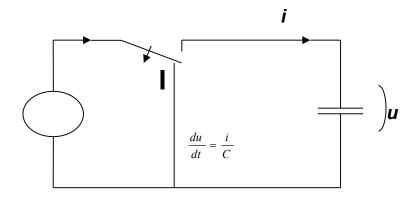
## BASIC turn on current step, capacitive load. No problem

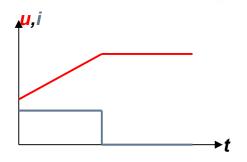




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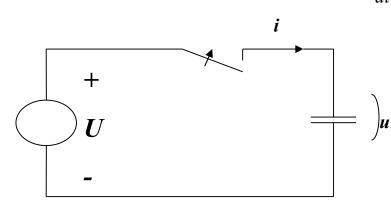
## **BASIC** turn off current step, capacitive load. No problem



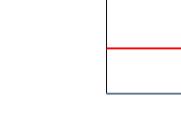


**Electric Drives Control** 

## **BASIC** turn on voltage step with capacitive load. Problem! $i = C \cdot \frac{du}{dt}$



 $U \neq u$ 

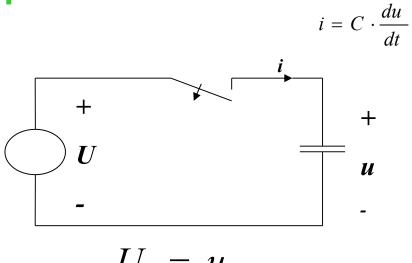


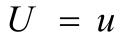
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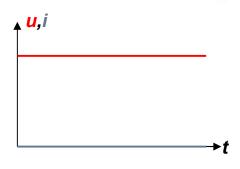
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Electric Drives Control

## **BASIC** turn off voltage step, capacitive load. No problem

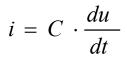


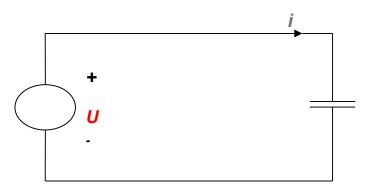


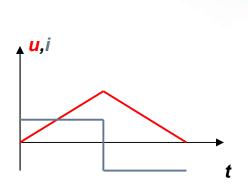


Electric Drives Control

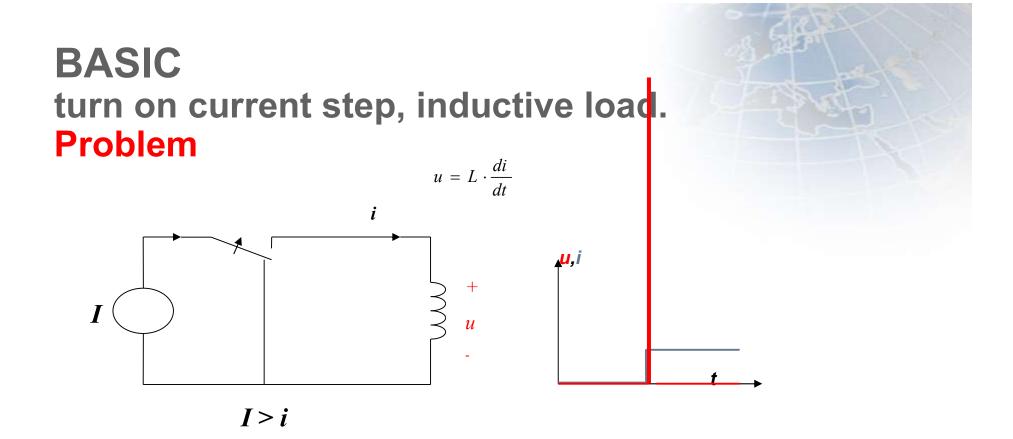
## BASIC voltage ramp, capacitive load. No problem



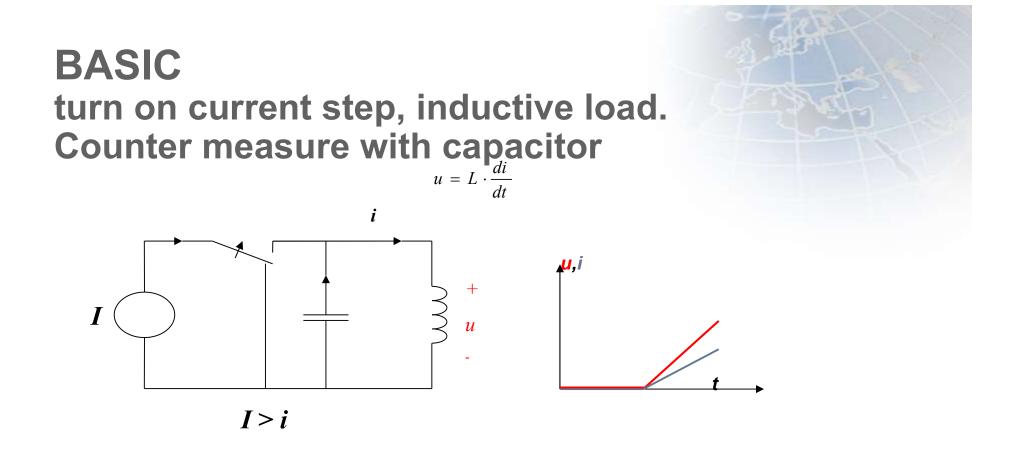




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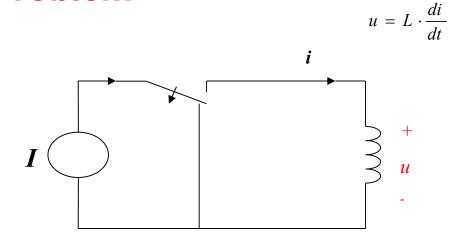


**Electric Drives Control** 



**Electric Drives Control** 

## BASIC turn off current step, inductive load. Problem

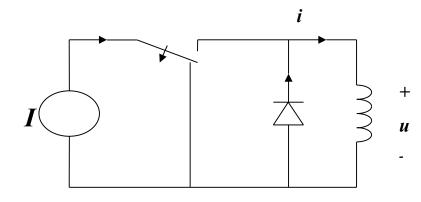


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## BASIC turn off current step, inductive load. Counter measure with freewheeling diode





**Electric Drives Control**