

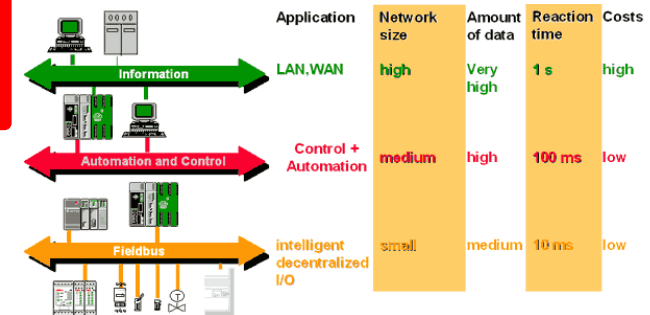
# Industrial Communication

Chapter 16

Gunnar Lindstedt

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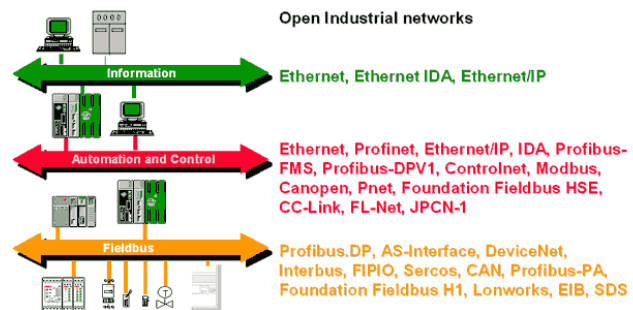
## Time and Data Ranges



Picture from:  
HMS Industrial Networks

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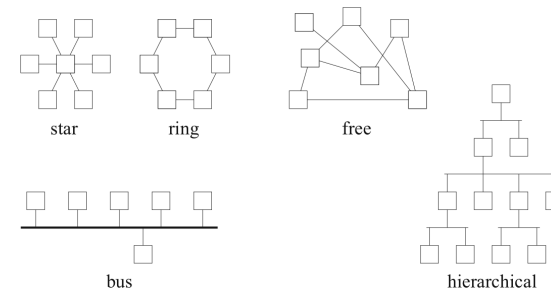
## Network "Products"



Picture from:  
HMS Industrial Networks

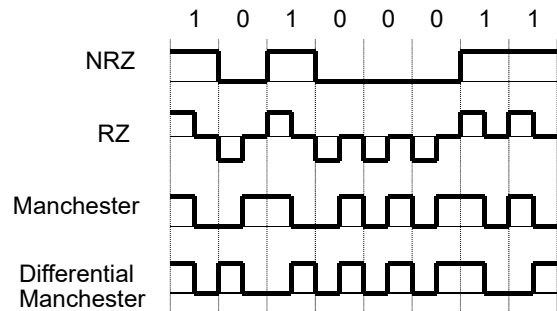
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## Network Topologies



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## Bit Coding Principles



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## Fundamentals

- Bandwidth,  $W$  (3 dB attenuation)
- Information,  $I = \log_2 N$  (bits). (N: number of symbols)
- Capacity (bits/s) - [ baud (symbols/s) ]
- Max. Cap =  $2 W \log_2(V)$  (noise free; V:# of levels)
- Max. Cap. =  $W \log_2(1+S/N)$  (theoretical)

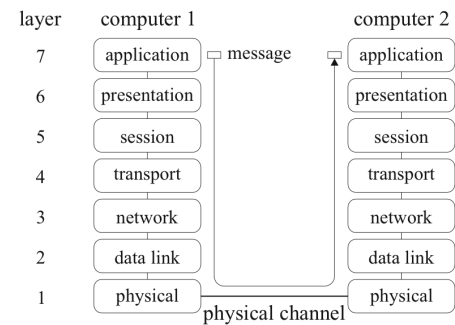
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## OSI

Open System Interconnection

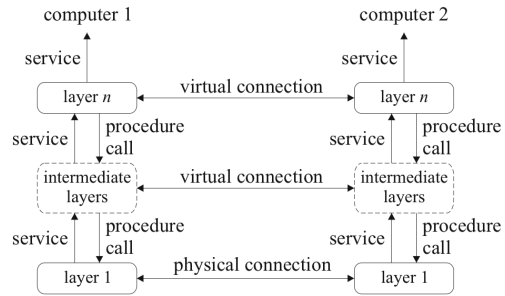
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## The OSI model



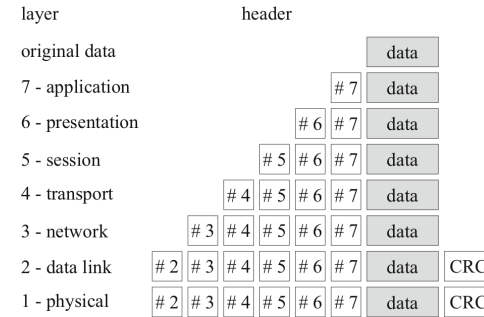
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# OSI peer-to-peer Communication



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# Layered Communication Protocols



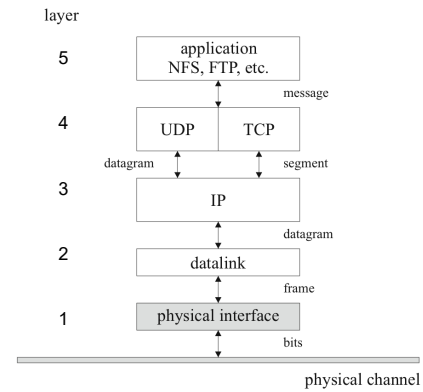
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# TCP/IP

Transmission Control Protocol / Internet Protocol

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# TCP/IP basic structure



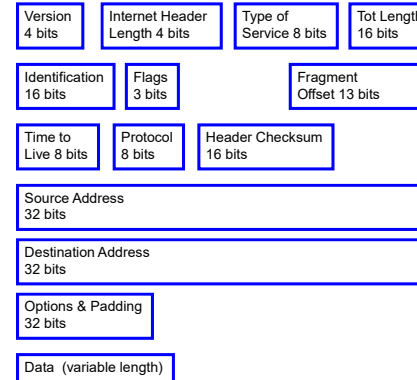
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## IP layer

- Responsible for moving datagrams from one point to another
- Unique, multicast or broadcast
- IP address 32 bits, Four 8-bit blocks, 0-255 (134.34.6.222)
- IP v4 in use - IP v6 in new products today

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## IP Datagram (IP v4)



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## TCP

- Single source – single destination
- Establish connection, transfer data, close connection
- Acknowledgement, retransmission
- Provide services for FTP,SMTP, TELNET
- TCP header

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## UDP

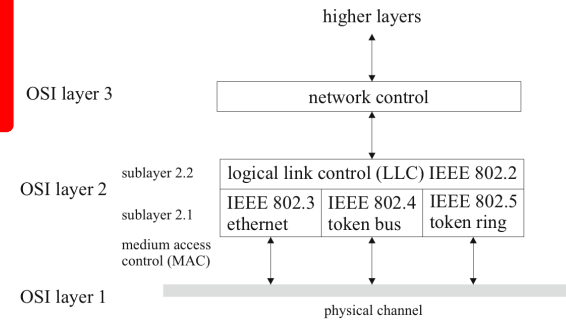
- Connectionless - unreliable
- Multicast and broadcast
- Applications
  - Data collection
  - Data presentation
  - Real time applications (audio)
- UDP header – less complex

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# Ethernet

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## IEEE/OSI level 2



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## Ethernet – Physical Layer

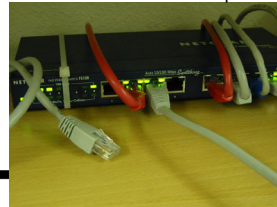
- Various media
  - Thick ethernet (10base5)
  - Thin ethernet, cheapernet (10base2)
  - TP, RJ45 (10baseT), cat5 (100baseT), cat5E (1000baseT), cat6 (10Gbase-T)

- Manchester coding

10base2 example



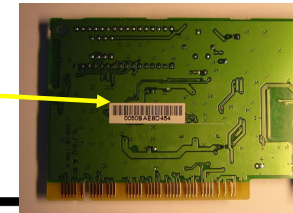
100baseT example



## Ethernet – data link

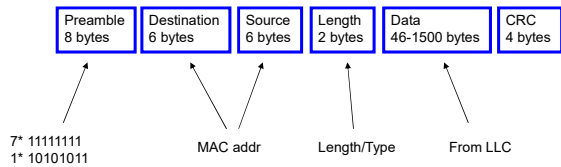
- CSMA/CD
  - Carrier-Sensing Multiple Access/Collision Detection
- MAC-address
  - Medium Access Control
  - 48 bit hardcode unique number

MAC address



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## The Ethernet Packet



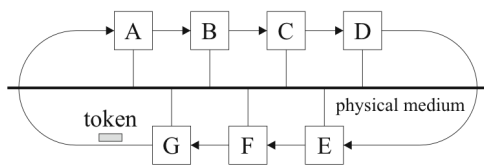
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## Ethernet - CSMA/CD

- Carrier-Sensing (check that the line is free)
- Multiple Access (begin a new transmission)
- Collision Detection (detect if the information is garbled)
- Some 50  $\mu$ s travel time = time slot
- **No real time guarantee!**

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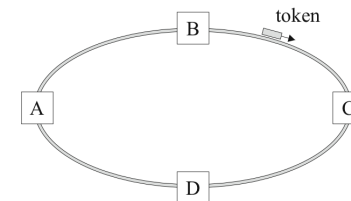
## Token Bus



**Deterministic!**

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## Token Ring



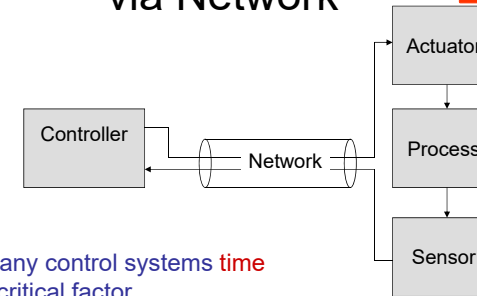
**Deterministic!**

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# Fieldbuses

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## Feedback and Control via Network



In many control systems time is a critical factor.  
Will this structure work?

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## Fieldbus

- Replace analog signals (cables) with a network
- Advantages
  - Easy installation
  - Simple maintenance
  - Less connection errors
  - Easy debugging
  - Simple reconfiguration
- Requires a new competence

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## Fieldbus Requirements

- Noise immunity
- Fast
- Real time performance (deterministic)

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## Fieldbus Features

- "The industrial automation LAN"
- About **100!** different buses aiming at different applications (cars, discrete manufacturing, continuous production).
- "Smart" nodes
- Not only sensor and actuator signals

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## Some Fieldbuses

- ASI
- PROFIBUS
- CAN
- DeviceNet
- ControlNet
- Interbus-S
- FIP
- Fieldbus Foundation

Overview information links:

<http://www.weighing-systems.com/TechnologyCentre/fieldbus1.html>

<http://www.pacontrol.com/download/fieldbuscomp.pdf>

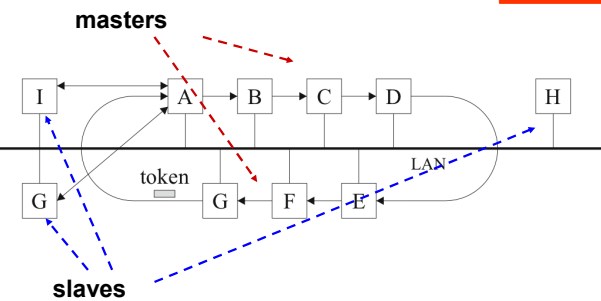
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## Profibus



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## PROFIBUS Principle



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## PROFIBUS

- Token bus with master/slave
  - 500k-12Mbit/s
  - RS485
  - Max 127 nodes (PA 256)
- <http://www.profibus.com>

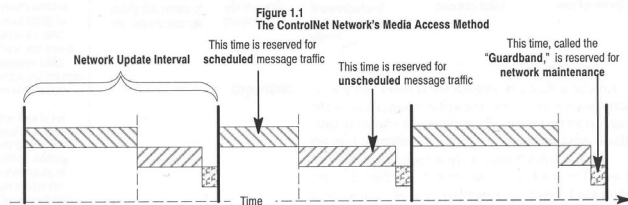
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## Most Fieldbuses are **not** deterministic by design!

- The fieldbus definitions include no tool for direct timing control.
- Token passing principles together with maximum data block size provides the real time performance.

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## ControlNet Timing



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## Deterministic Fieldbus Examples

- ControlNet <http://www.odva.org>
- TTP <http://www.tttech.com>
- Foundation Fieldbus <http://www.fieldcommgroup.org>
- EtherCAT <http://www.beckhoff.com>

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## Ethernet TCP/IP a fieldbus?

- Not by design!
- Today it is being (mis-)used (?)
- High performance – low cost
- Speed and limited load compensates for real time performance and determinism
- Development of "Lean TCP/IP stacks" - IoT
- Redefined?



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## Summary

- Communication is a key technology in automation
- Network topologies
- OSI
- Ethernet and TCP/IP
- Deterministic vs. non-deterministic
- Fieldbuses

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## HMI

### Human-Machine Interface

[ MMI, MMC ]

(HMI chapter from previous book edition 1992, [excerpt](#))

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## Goals

- Understand the different purposes with HMI in Automation
- Know basic HMI design rules
- Be familiar with terms like "tagname database" and "animation links"
- In general terms understand the integrations of an HMI in a PLC system.

## Human and machines compensate for each other

- Power
- Speed
- Attention - alarms
- Memory
- "Intelligence"
- Rule based thinking
- Symbolic information

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## Human and machines have to adjust to each other

- We can not have systems that humans can not handle
- High education and training more and more required

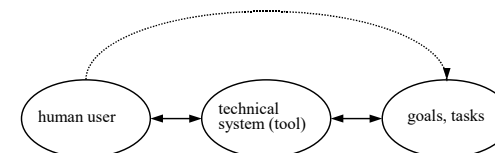
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## Different HMI views @ IEA

- Situation awareness
  - Dr. Lawrence Jones; Power applications
- Usability
  - Master thesis; Anders Lyddby
- Complexity reduction
  - Tech Lic; Gianguido Piani

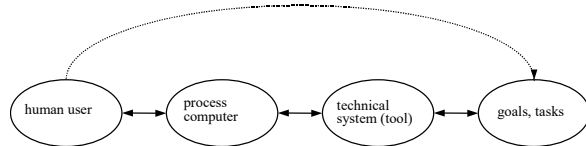
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## Interactions



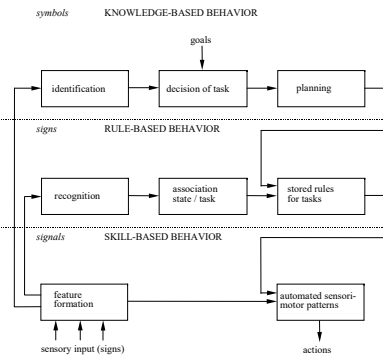
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## The Process Computer as a View into the Process



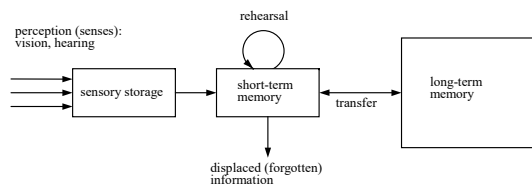
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## Levels of Human Performance



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## Dual Memory Model



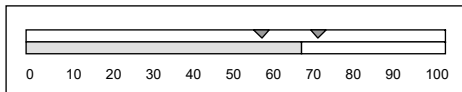
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## Remember...

- Previous experience is powerful
- Social and cultural background
- Educational level
- Objectives and motivation

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## Intuitive Presentation



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## Message (1)

A502 POWERED: YES/NO

A502 POWER: ON/OFF

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## How to Remember?

4687834000

or

46 - 8 - 783 4000

- Remember the 7 +/- 2 rule!

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## About Color

- Powerful but dangerous
- 4-5 possible to understand. (Abs max: 7)
- Consistent use
- Redundancy needed
- Blink attribute on symbols - **not on text**

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## Some Experiences of the Operator Role (1)

- The user HAS to be part of the design
- The system has to be able to grow according to the demands
- Easy interpretation of the man-machine interface

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## Some Experiences of the Operator Role (2)

- Mental models have to be pictured
- TIME is a difficult variable to show!
- The system has to **help** the operator, not to be another burden!
- Reality is not a flat screen
- Different users need different presentations

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## InTouch demo

- Tagnames
- Animation links

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